

-The situation of simple operation and easy control

Page 51 System wiring diagrams

52 Specifications and characteristics of Motor/Driver

53 Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD2)

53 Motor allowable radial load/axial load

Speed - Torque characteristic diagrams

55 Driver panel functions and wiring instructions

56 Motor electromagnetic brake wiring instructions

57 Dimensions - Motor/Gearhead

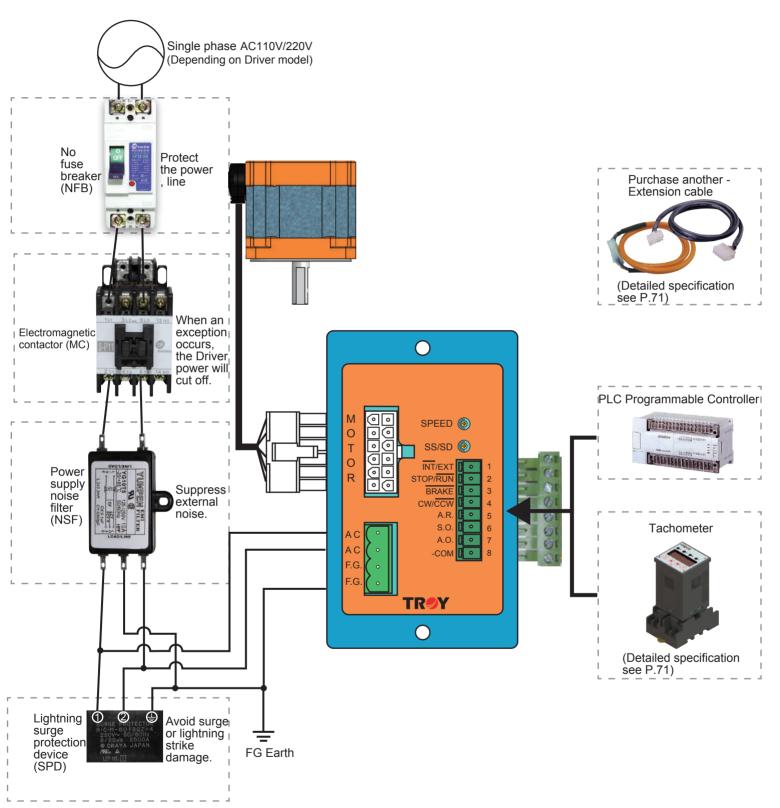
59 Dimensions - Driver

59 Dimensions - Power supply noise filter



DC brushless Motor- UBS series

■ System wiring diagrams



- Power supply noise filter (NSF):
- Our company's products comes with 10A power supply noise filter.
- •Lightning surge protection device (SPD) wiring precautions: Different brands have different wiring, refer to each original proposal to do the wiring diagram wiring.



■ Specifications and characteristics of Motor/Driver

Мо	tor output pov	wer	20W	40W	60W	90W
	und shaft Motor (Mion shaft Motor (M		6B020S-□N(M) (Note 1) 6B020P-□N(M)	6B040S-□N(M) 6B040P-□N(M)	9B060S-□N(M) 9B060PD-□N(M)	9B090S-□N(M) 9B090PD-□N(M)
Mot	tor specification	-1 Type	Ç⇔ RoHS	⊕ IP54	RoHS	 De
cert	tificates	-2 Type		oHS) (P54	€ ((((((((((RoHS (Note 2)
Driv	/er		UBD020-□N	UBD040-□N	UBD060-□N	UBD090-□N
Driv	er specification	certificates		CE Ro	DHS @	
Inp	-1 Type Single Phase	Max. Current (A)	2.4	2.4	2.5	2.9
ut pov	AC110~115V 50/60 HZ	Rated Current (A)	0.59	0.99	1.48	1.93
	-2 Type Single Phase AC220~230V	Max. Current (A)	1.7	1.7	1.7	1.7
tage	AC220~230V 50/60 HZ	Rated Current (A)	0.33	0.56	0.82	1.05
Star	ting Torque (Nm)		0.15	0.25	0.45	0.65
	ed Torque (Nm)		0.10	0.20	0.30	0.50
۹llo۱	wable load inertia	GD ² (Kgcm ²)	14.01	23.23	39.42	54.23
	S S Input line	• , ,	DC		DC	
E/M	Consumpt	ion power(W)	6.1	-		.5 .5
E/M Brake	Series have Ease ti		30		_	3
ê	Release ti		87			5
Spe	ed control range(r	· · · ·		250~	2000	
		To load	-1%Max.	at 2000r/min, no load~ra	ted load.	
Spe	ed variation rate	To voltage	±2%	Voltage variation ±15%,	at 2000r/min, no load.	
		To Temperature	±2%	0-+40°C at 2000r/min, no	o load.	
Slov	w start/Slow down	time set up		tor from 0~2000r/min who tor from 2000~0r/min who		
Spe	ed control method	d	Controlled by front pan Controlled by back pan	•		
			Photo coupler input interest.			
Sigr	nal input/output m	ethods	Transistor Open Collect			
			,		m the front panel "RUN /	
Fun	ction		· ·		vithin the speed control ra op (SLOW START / SLOV	•
			When brake to stop all	• •	op (SEOW STAIRT / SEOV	
			When protective function	is activated, Motor will co	oast to a stop drive ALAR	M contact signal output
				it starts operation	ited torque of Motor runni	
Prot	tection function			· (1)Up and down, windir		ceeds 80 ° C, starts operation le load inertia during operat
			_	(2)When Driver voltage	of the AC power input mo	ore than about 35%,
			=		voltage is lower than abou	it 20%, starts operation
La				: When Motor cable disc	· '	
ınsu	llation impedance					resistance value is over 100M
Insu	llation high voltage	Э	Power and F.G connect to connectors pass with 3K	to ground, terminals pass V/60Hz high voltage for 1	with 1.8KV/60Hz high vo minute, no abnormal cor	Itage, power and I/O
1 mb	nient temperature/	Humidity range	0~+40°C, under 85% rel	ative humidity (avoid dus	t and erosion, combustion	n nas)

Note1 : -□, Please fill power voltage in □. ⊡indicates single phaseAC110~115V , ②: indicates single phase AC220~230V * 1 Nm=10.19716 Kgcm_Note2 : 9B060PD-2N \ 9B090PD-2N have passed IP54 certificate.

വന വന്നാ Accessories Motor selection



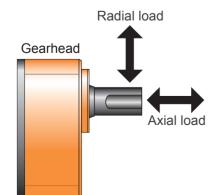
■ Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)

Gea	r ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30
Speed range	High speed	666	555	400	333	266	222	200	160	133	111	100	80	66
(r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8.4
Allowable torque (Nm)	6B020P-□N(M) + 6D□	0.27	0.32	0.45	0.54	0.68	0.81	0.9	1.1	1.4	1.6	1.8	2.2	2.6
Allowable inert	tia load GD ² (kgcm ²)	6.30	9.08	17.5	25.2	39.4	56.7	70.1	109	158	227	280	438	625
Allowable torque (Nm)	6B040P-□N(M) + 6D□	0.54	0.65	0.9	1.1	1.4	1.6	1.8	2.3	2.7	3.2	3.6	4.3	5.2
Allowable inert	tia load GD² (kgcm²)	10.5	15.1	29.0	41.8	65.3	94.1	116	181	261	376	465	62	25
	9B060PD-□N(M) + 9D□	0.81	0.97	1.4	1.6	2	2.4	2.7	3.4	4.1	4.9	5.4	6.5	7.7
Allowable iner	tia load GD ² (kgcm ²)	63.1	90.8	175	252	394	568	701	1095	1577	2271	2803	4380	6307
	9B090PD-□N(M) + 9D□	1.4	1.6	2.3	2.7	3.4	4.1	4.5	5.6	6.8	8.1	9	10.8	12.9
Allowable iner	rtia load GD ² (kgcm ²)	86.8	125	241	347	542	781	964	1506	2169	3124	3856	6026	8677
							100			100				
Geal	r ratio	36	50	60	75	90	100	120	150	180	200	250	300	360
Speed range	High speed	55	40	33	26	22	20	16	13	11	10	8	6	5
(r/min)	Low speed	7	5	4.2	3.4	2.8	2.5	2.1	1.7	1.4	1.3	1	0.9	0.7
Allowable torque (Nm)	6B020P-□N(M) + 6D□	3.1	4.3	5.2		6.5					6.5			
Allowable inert	tia load GD ² (kgcm ²)			62	25						625			
	6B040P-□N(M) + 6D□	6.2			6.5						6.5			
Allowable inert	tia load GD ² (kgcm ²)			62	25						625			
	9B060PD-□N(M) + 9D□	9.3	12.9	15.5	19.4	23.2	25.8	29.2	36.5			40		
Allowable inert	tia load GD² (kgcm²)	9082			110	00					11000			
	9B090PD-□N(M) + 9D□	15.5	21.5	25.8	32.3	38.7	40				40			
Allowable iner	rtia load GD² (kgcm²)			110	000						11000			

- *Motor 6B020P-□(M)...etc, please fill in □ with line power voltage. 1 : stand for single phase AC110~115V, 2 : stand for single phase AC220~230V.
- *Gearhead 6D \(\textstyle \)/9D \(\textstyle \)/9D \(\textstyle \)/H, please fill gear ratio in \(\textstyle \).

 In above table stands for after installation of Gearhead, the axis rotation direction is reversed with Motor axis direction; without marking stands for the same direction as Motor axis rotation.
- * 1Nm = 10.197Kgcm.
- *The Gearheads of all series have RoHS @ certificate.
- * Also available orthogonal Gearhead: hollow shaft type $9VD\square(H)$, the solid single shaft type $9VD\square A(H)$, the solid biaxial shaft type $9VD\square B(H)$, and size please refer to P.10.

■ Motor allowable radial load/axial load



- Radial load (hanging load): loading is vertical to Gearhead axis power output
- Axial load (thrust load): loading is in the direction of Gearhead axis power output

◆ Round shaft type

Model	Permissible overhur	ng load (Unit: Kg f)	Permissible thrust load
	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)
6B020S-□N(M)	8	9	Permissible axial loading, not more than 1/2 of motor weight. But please try to avoid applying
6B040S-□N(M)	8	9	force in the horizontal direction (axial) of motor shaft, when
9B060S-□N(M)	13	15	exceeds that will reduce motor service life. If axial loading is needed, we
9B090S-□N(M)	16	17	recommend applying indirect transmission, such as: couplings, belts, chains, etc

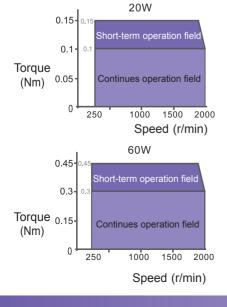
◆ Pinion shaft type (Gearhead attached)

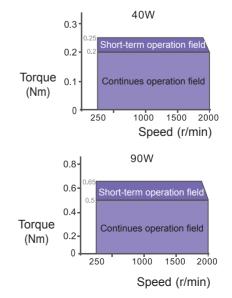
		Permissible overhu	ng load (Unit: Kg f)	Permissible thrust load
Model	Gear ratio	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)
6B020P-□N(M)	3, 3.6, 5	10	15	
+ 6D□ 6B040P-□N(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	15	20	4
+ 6D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	20	30	
9B060PD-□N(M)	3, 3.6, 5	30	40	
+ 9D□ 9B090PD-□N(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15
+ 9D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65	

* Motor 6B020S-□N(M)... etc, please fill power voltage in □. □ : indicate single phase AC110V~115V, □ : indicate single phaseAC220~230V

* Gearhead 6D□/9D□, please fill Gearhead in □.

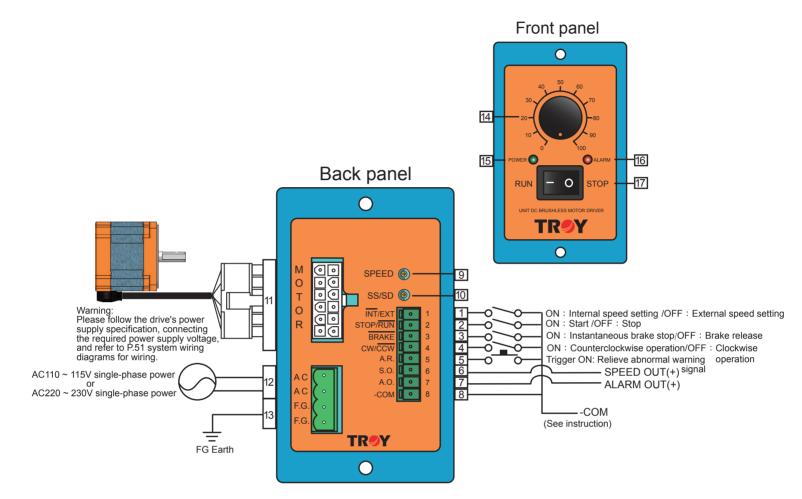
■ Speed - Torque characteristic diagrams







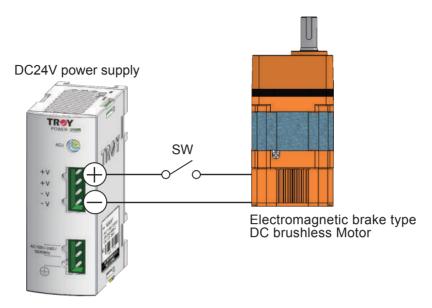
■ Driver panel functions and wiring instructions



Number	Panel marked	Function	Explanation
1	ĪNT/EXT	Speed setting mode switch to select the input	Internal / external speed setting mode switching selection
2	STOP/RUN	Stop/Start signal input	Stop / start signal switching input
3	BRAKE	Instantaneous brake stop signal input	Executive instantaneous brake stop / brake release signal switch input
4	CW/CCW	The direction of rotation switch to select the input	Clockwise/counterclockwise operation switch selection
5	A.R.	Warning signs release abnormal input	AR trigger input contacts (continuous "L" state 10ms) to release the error warning signal
6	S.O.	Speed signal output	When Motor speed is detected using, digital signal output 12 Pulse / rev
7	A.O.	Abnormal warning signal output	Overload, overheating, over voltage, low voltage, disconnection of any of a protective function is activated, Motor stops naturally, and outputs an abnormality warning signal
8	-COM	Controlling signal grounding	GND contact inputs and outputs a control signal common ground wire, and the external DC power
9	SPEED	Speed setting button	20~90W speed control range: 250~2000r/min
10	SS/SD	Slow start, stop time setting button	Slow start 0.5~8sec; slow stop 0.5~7sec
11	MOTOR	Motor wiring connector	Motor and Driver connection
12	AC	Power voltage input terminal	AC power voltage input connection
13	FG	Power ground terminal	Power ground connection
14	Scale button	Speed setting button	Rotating the knob clockwise to adjust the Motor speed from slow to fast speed range: 250 ~ 2000r/ min
15	POWER	Power indicator	Input Power LED (green) lights
16	ALARM	Unusual indicator	Overload, overheating, over-voltage, low voltage, disconnection of any of a protective function is activated LED (red) lights
17	RUN/STOP	Start / stop switch	Start / stop switch

S

■ Motor electromagnetic brake wiring instructions



Operation instruction

Motor start/Motor stop with external electromagnetic brake operating procedures: Motor start: Must energize external electromagnetic brake before the Motor starts

Step :	External electromagnetic brake power ON
	Attracting waiting time (This is the time of the external electromagnetic brake actuation, the purpose: to keep the force is released)
	Motor Driver starting signal ON
	Motor starts running
Motor Stop :	The Motor is stopped before the operation do not yet fully external electromagnetic brake power.
Step :	Motor Driver stop signal ON
	Wait 0.2sec (reference value, this is the operation of the Motor to a complete stop time)
	External electromagnetic brake power is turned OFF
	Waiting for the release time (This is the external electromagnetic brake actuation time, purpose: To generate holding force)
	Motor stopped (a holding force)

Precautions

1. This series of external electromagnetic brake using the brake power is part of the hold-type. 2. External electromagnetic brake is designed to allow the Motor stops when the holding force

has to be used as a safety brake, electromagnetic brake, do not use this as a Motor positioning or emergency brake applications.

3. Always to pull the Motor before starting the external electromagnetic brake energized (means no brakes); Motor stopped before the operation do not yet fully external electromagnetic brake power (expressed brakes)

4.External electromagnetic brake suction time and release time value refer to the product specification. 5. Motor brakes to stop for about 0.2sec (test conditions in the Motor no-load speed 3000r / min, the electromagnetic brake is energized, the brake actuator signal ON time of the Driver, this time as a reference base, but the actual length of time will stop according to the inertia load or frictional load different load patterns and has fluctuated.

6.We recommend to do the actual measuring device operating time at the time of commissioning.



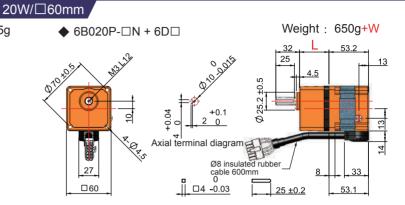
Dimensions - Motor/Gearhead

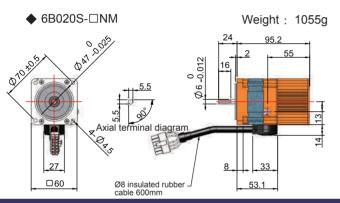
Unit: mm

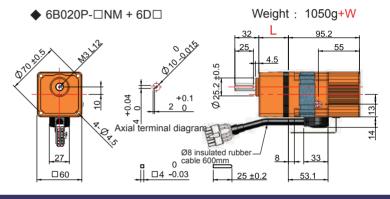
Round shaft type

Gear shaft type

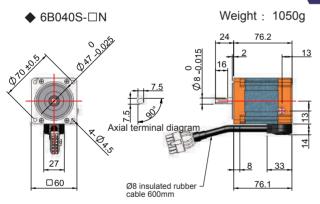
◆ 6B020S-□N Weight: 655g Axial terminal diagram Ø8 insulated rubber cable 600mm

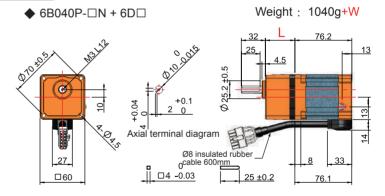


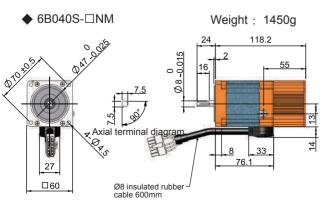




40W/□60mm







6B040P-□NM + 6D□

Weight: 1440g+W

* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

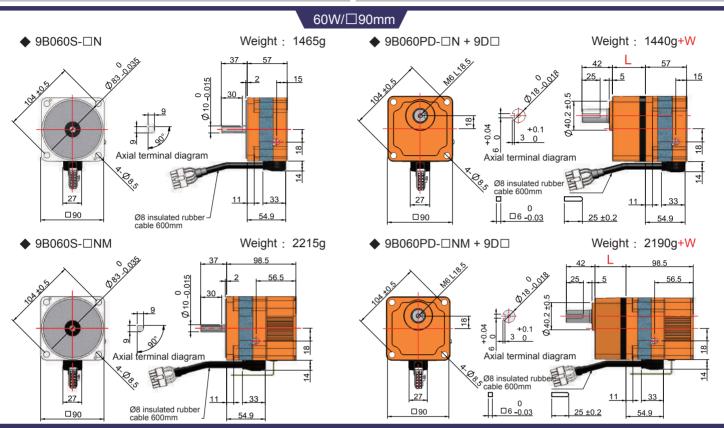
*6B pinion shaft type 6D3-6D360, Gearhead length L and weight W specification as following:

	Model	6D3~6D20	6D25~6D100	6D120~6D360
Gearhead	Length L (mm)	39.5	39.5	43.5
	Weight W (g)	300	325	365

Unit: mm

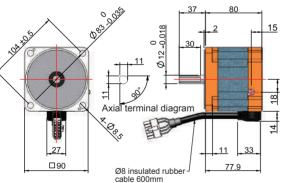
■ Dimensions - Motor/Gearhead

Round shaft type Gear shaft type



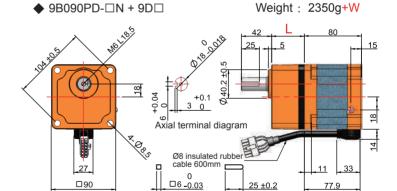
90W/□90mm

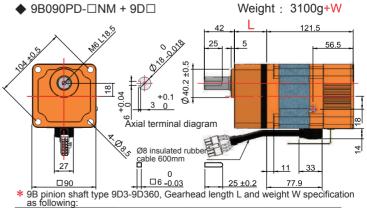
♦ 9B090S-□N Weight: 2380g



◆ 9B090S-□NM Weight: 3130g 70A.x0.52 Axia terminal diagram Ø8 insulated rubber cable 600mm

* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.





Model 9D3~9D20 9D25~9D100 9D120~9D360 ead Length L (mm 45.5 58.5 64.5 Weight W (g) 860 1125 1265



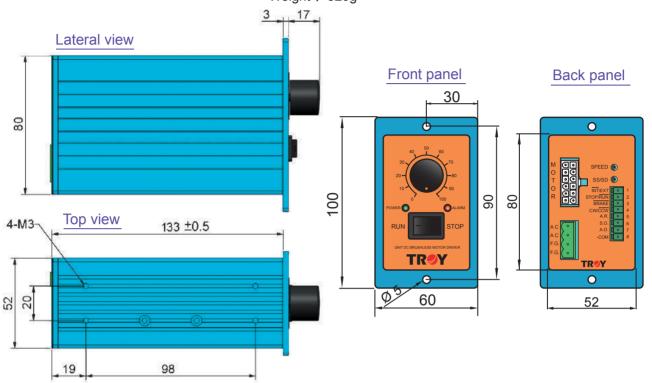
■ Dimensions - Driver

Model : UBD020-□N/UBD040-□N Dimensions are common Unit : mm

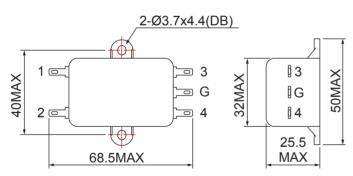
UBD060-□N/UBD090-□N

Weight: 50g

Weight: 520g



■ Dimensions - Power supply noise filter



* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

■ Machanism: 【Op	perating of larg	e index tal	ole]		Date dd/mm/yy
Company name:	Co	ntact perso	n:	Department/T	ītle:
TEL:	FAX:		Application:	Use a	area:
Power input: □Single	e -phase AC:	V □Three	e-phase AC:V	□DC: <u>V</u>	Frequency: Hz
□9 s □0	Regulated speed single direction retop time: Section to the section retop time in the section retords and the section retords are section retords and the section retords are section r	(Range: un \ stop \ r ond/Sequer er clockwise Sequence \	_ rpm ~ rpm)	/ated time: \$ IlSequence :Second/Se	, , , , , , , , , , , , , , , , , , ,
DC □D	orque brushless motor BS Series	: □BMS Se	□Reversible □S ries □BS Series phase □5 phase		
(Mechanism referer	nce]	-	ase sketch your ac of mechanism]	tual transmissi	on
Obje					
Drive mechanism a	and operating da	ta 】			
Obj	ect mass		W =	kg	
Inde	ex table diamete	r	DT =	cm	
Wid	th		LT =	cm	
Mat	erial		ρ =		
Pos	itioning angle	*(note)	θ =	deg	
Pos	itioning time	*(note)	To =	sec	
Sto	pping accuracy		±	mm	
*(nc	te)Please enter	the max sp	eed		
Recommendation pro	oducts (Selecte	d specs) :			

After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

■ Machanism:	Lead	screw]					D	ate dd/mn	n / yy
Company name:			Conta	ct person:		Departn	nent/Tit	le:	
TEL:		FAX:			Application:		Use ar	ea:	
Power input: □Si	ngle -pl	nase AC	:V	□Three	-phase AC:V	□DC:	V	Frequency:	Hz
Activated mode:	□Regu □Singl stop □Clock	ulated sp le direction time: kwise/co : Seco	eed (Ron run Seconominate conditions)	ange: stop \ ru d/Sequen lockwise	tinuously → □Rat rpm ~rpm) un · stop → (Activ ce; Run, stop total repeated → (CW: CCW:Second/	ated tin	ne: S quence : cond/Se	/Minutes)	uence,
·	□Torqu DC brus □DBS	e shless m Series	notor: □	IBMS Ser	□Reversible □Spies □BS Series □ Dhase □5 phase				
Mechanism ref	W	Dbject Level	W a		Please sketch part of mechan	-	ctual tra	nsmission	
Drive mechanis	sm and	operatin	g data)						
Work+Table m	ass		W = _	kg	frictional coeffici	ent of		μ =	_
Screw angle			$\alpha = $ _	deg	sliding surfaces			L =	
Screw shaft di	ameter		D _B = _	cm	Positioning dista	ance	*(note)	To =	_sec
Screw Length			L _B = _	cm	Positioning time		*(note)	F _A =	_kg
Screw pitch			P _B = _	cm	Push / Pull force			±	
Material			ρ = _		Stopping accura	асу			
Screw efficien	су		$\eta = $ _						
Internal friction	nal coef	ficient of	# μ ₀ =_						
pilot pressure	nut				*(note)Please e	nter the	e max s	peed	

Recommendation products (Selected specs) :

^{*} After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

■ Machanism: 【	Belt ar	nd pulle	ey]						ate dd/mm	1 уу
Company name:			Contact p	person:		I	Departr	nent/Ti	tle:	
TEL:		FAX:			Application	:		Use a	rea:	
Power input: □Si	ngle -ph	ase AC:	V 🗆	Three	-phase AC:	V	□DC:	V	Frequency:	Hz
Activated mode:	□Regul □Single stop ti □Clock	ated specification at the second seco	eed (Rangon run se Second/Sunter cloc	ge: top \ ru Sequen kwise ence \	rpm ~rp	m) (Activ p total (CW:	ated tin	ne: uence :ond/Se		ience,
]]	□Torque DC brusl □DBS S	e hless m series	otor: □BN	ฟS Ser		eries I			⊐Magnetic bi □UBS Serie	
DP2 FA	Object Le		Motor	_	ase sketch y t of mechani		ctual tra	ansmis	sion	
Drive mechanis	sm and o	perating	g data]							
Work + Table +	Pulley	W =	kg	Belt `	pulley efficie	ency			η =	
Screw angle		α =	deg	friction	nal coefficien	t of sl	iding su	urfaces		
Pulley diamete	r	D _P 1 =	cm		oning distand	•	ote)		L =c	m
Width		L _P 1 =			oning time *(note)			To=s	
Material				Push /	Pull force				F _A =k	
Pulley diamete			cm	Stopp	ing accuracy	′			±r	nm
Width		L _P 2 =								
Material		ρ2 =		*(note	Please ente	r the	max sp	eed		

 $\label{lem:Recommendation products} \mbox{ (Selected specs) } \mbox{ : }$

^{**} After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

Company name:		Contact person:	•	Departi	ment/Ti	tle:	
	FAX:		Application:		Use a		
Power input: ☐Single -t	hase AC	· V DThree		V ΠDC·			Hz
□Sing stop □Clo Sto Sto Sto Required motor: AC ind □Torq DC bri	gle direction direction direction direction direction module.	on operating conceed (Range: on run \ stop \ ru Second/Sequen ond/Sequence \ uence/Minute) otor: □Induction	tinuously → □I rpm ~rpm) un · stop → (Acce; Run, stop to repeated → (C' CCW:Seco	Rated spectivated tire of talSection Sequel Speed constants.	me: \$ quence cond/Se nce \	/Minutes) equence	ake
C Drive mechanism and mechanism and fill in	d operatin	_	he space below		he outli	ine of your dri	

applicable product for you as soon as possible