

-For fast response speed, high operation frequency demand

System wiring diagrams
Specifications and characteristics of Motor/Driver
Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)
Motor allowable radial load/axial load
Speed - Torque characteristic diagrams
Driver panel functions and wiring instructions

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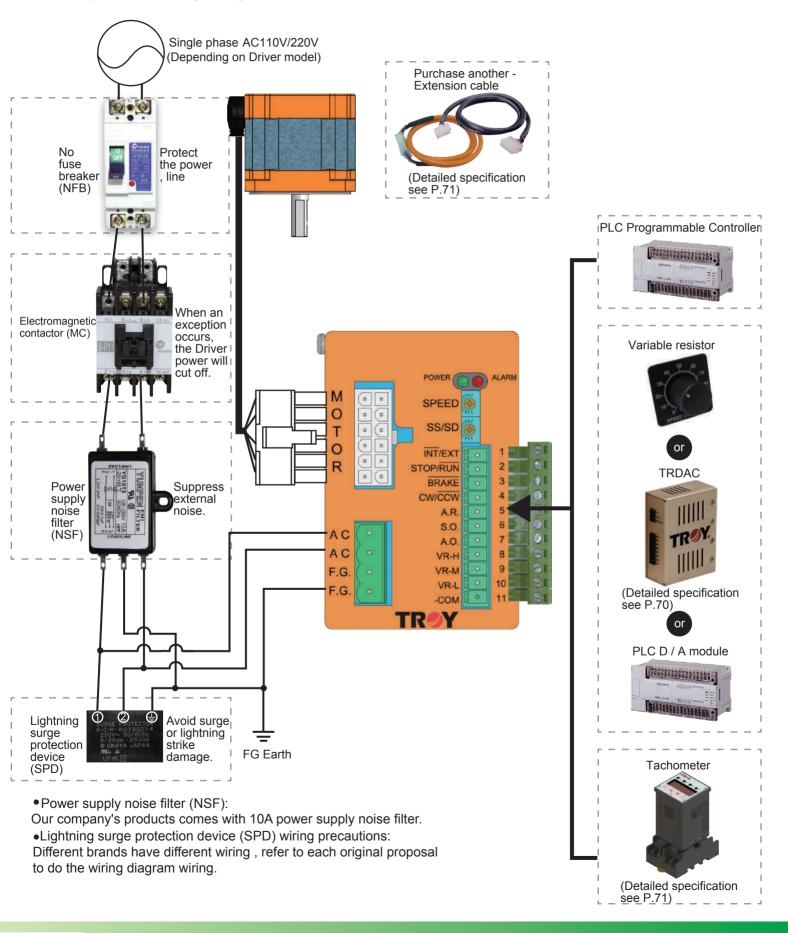
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Dimensions - Variable resistor/Power supply noise filter



DC brushless Motor- SBS series

■ System wiring diagrams



6B040P-2N

■ Specifications and characteristics of Motor/Driver

Mc	ntor o	utput pov	ver	20W	40W	60W	90W
			M: E/M brake type) E/M brake type)	6B020S-□N(M) (Note 1) 6B020P-□N(M)	6B040S-□N(M) 6B040P-□N(M)	9B060S-□N(M) 9B060PD-□N(M)	9B090S-□N(M) 9B090PD-□N(M)
Мо	tor spe	ecification	-1 Type	C US RoHS)⊕ IP54	RoHS	9
	tificate		-2 Type	(€ ((() F	юн s • IP54	(E)	RoHS (Note 2)
Dri	ver			SBD020-□N	SBD040-□N	SBD060-□N	SBD090-□N
Dri	ver sp	ecification (certificates		(€ Ra	нѕ 🗨	
Б			Max. Current (A)	2.4	2.4	2.5	2.9
it po	AC110 ⁻ 50/60 F		Rated Current (A)	0.59	0.99	1.48	1.93
Input power voltage	-2 Type AC220		Max. Current (A)	1.7	1.7	1.7	1.7
ltage	50/60 H		Rated Current (A)	0.33	0.56	0.82	1.05
Sta	rting To	orque (Nm)		0.15	0.25	0.45	0.65
		que (Nm)		0.10	0.20	0.30	0.50
Allo			GD ² (Kgcm ²)	14.01	23.23	39.42	54.23
	* Only E/M braseries have	Input line v		DC		DC	
F/≥	ly E/ ïes h	Maintenan	on power(W)	6.		7.	
F/M Brake	M bi	Attraction t		3			3
ô	rake E/M	Release tin		8		9	
Spe		trol range(r/	min)		250~	2000	
		Т	o load	-1%Max.	at 2000r/min, no load~rate	ed load.	
Spe	ed vari	ation rate T	o voltage	±2%	Voltage variation ±15%, a	t 2000r/min, no load.	
		T	o Temperature	±2%	0-+40°C at 2000r/min, no	load.	
Slov	w start/	Slow down t	ime set up	,	tor from 0~2000r/min whe tor from 2000~0r/min whe	n no load	
Spe	ed con	trol method			rariable resistor (resistanc ariable resistor al variable resistor for 2 se	(DC0~5\//1 p	external DC voltage nA above) A speed setter TRDAC
Siar	nal inpu	ut/output me	thods	●Photo coupler input into		()	
- 3				Transistor Open Collect		-t D-l t 1/0 d-l	1-
				•	connect to PLC or Transiange, Motor sets Flat Torq		ie
- un	ction			●Instant brake stop, Slo	0 /		
				· ·	lectric types of holding role	е	
				Can parallel operation			
Prof	tection	function		Overload protection: st Over heat protection: s Over voltage protection Low voltage protection	ns activate, Motors stop a arts when Motor activate in tarts when Driver internal n: (1) starts when up down (2) When Driver voltage operation n: Driver input AC power ven Motor cable disconnection	torque for more than 7 set heat sink over 80°C n, coiling or over inertial lo ge of the AC power input o oltage is lower than about	c ad over about 35%, starts
Insu	ulation i	mpedance		Applies DC500V high res	istance meter test, power, F	G grounding, I/O terminal r	resistance value is over 100MΩ
		high voltage			to ground, terminals pass	<u> </u>	
		mporaturo/L	lumidity range		lative humidity (avoid dus		

Note1 : -□, Please fill power voltage in □. □indicates single phaseAC110~115V , ②: indicates single phase AC220~230V * 1 Nm=10.19716 Kgcm Note2: 9B060PD-2N 9B090PD-2N have passed IP54 certificate.



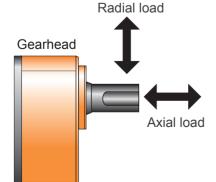
SBS series

■ Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)

Gear	ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30
Speed range	High speed	666	555	400	333	266	222	200	160	133	111	100	80	66
(r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8.4
Allowable torque (Nm)	6B020P-□N(M) + 6D□	0.27	0.32	0.45	0.54	0.68	0.81	0.9	1.1	1.4	1.6	1.8	2.2	2.6
Allowable iner	rtia load GD ² (kgcm ²)	6.30	9.08	17.5	25.2	39.4	56.7	70.1	109	158	227	280	438	625
Allowable torque (Nm)	6B040P-□N(M) + 6D□	0.54	0.65	0.9	1.1	1.4	1.6	1.8	2.3	2.7	3.2	3.6	4.3	5.2
Allowable iner	tia load GD² (kgcm²)	10.5	15.1	29.0	41.8	65.3	94.1	116	181	261	376	465	62	25
Allowable torque (Nm)	9B060PD-□N(M) + 9D□	0.81	0.97	1.4	1.6	2	2.4	2.7	3.4	4.1	4.9	5.4	6.5	7.7
Allowable iner	tia load GD² (kgcm²)	63.1	90.8	175	252	394	568	701	1095	1577	2271	2803	4380	6307
Allowable torque (Nm)	9B090PD-□N(M) + 9D□	1.4	1.6	2.3	2.7	3.4	4.1	4.5	5.6	6.8	8.1	9	10.8	12.9
Allowable inert	tia load GD² (kgcm²)	86.8	125	241	347	542	781	964	1506	2169	3124	3856	6026	8677
Gea	r ratio	36	50	60	75	90	100	120	150	180	200	250	300	360
Speed range	High speed	55	40	33	26	22	20	16	13	11	10	8	6	5
(r/min)	Low speed	7	5	4.2	3.4	2.8	2.5	2.1	1.7	1.4	1.3	1	0.9	0.7
Allowable torque (Nm)	6B020P-□N(M) + 6D□	3.1	4.3	5.2		6.5					6.5			
Allowable inert	tia load GD² (kgcm²)			62	25						625			
Allowable torque (Nm)	6B040P-□N(M) + 6D□	6.2			6.5						6.5			
Allowable inert	tia load GD² (kgcm²)			62	25						625			
Allowable torque (Nm)	9B060PD-□N(M) + 9D□	9.3	12.9	15.5	19.4	23.2	25.8	29.2	36.5			40		
Allowable iner	tia load GD² (kgcm²)	9082			110	000					11000			
Allowable torque (Nm)	9B090PD-□N(M) + 9D□	15.5	21.5	25.8	32.3	38.7	40				40			

- * Motor 6B020P- \square (M)...etc, please fill in \square with line power voltage. $\boxed{1}$: stand for single phase AC110~115V, $\boxed{2}$: stand for single phase AC220~230V.
- * Gearhead 6D □ /9D □ /9D □ H, please fill gear ratio in □.
- * In above table stands for after installation of Gearhead, the axis rotation direction is reversed with Motor axis direction; without marking stands for the same direction as Motor axis rotation.
- *1Nm = 10.197Kgcm.
- *The Gearheads of all series have RoHS @ certificate.
- *Also available orthogonal Gearhead: hollow shaft type $9VD\square(H)$, the solid single shaft type $9VD\square A(H)$, the solid biaxial shaft type $9VD\square B(H)$, and size please refer to P.10.

■ Motor allowable radial load/axial load



- 1 Radial load (hanging load): loading is vertical to Gearhead axis power output
- 2 Axial load (thrust load): loading is in the direction of Gearhead axis power output

B S

◆ Round shaft type

Model	Permissible overhun	g load (Unit: Kg f)	Permissible thrust load
Model	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)
6B020S-□N(M)	8	9	Permissible axial loading, not more than 1/2 of motor weight. But please try to avoid applying
6B040S-□N(M)	8	9	force in the horizontal direction (axial) of motor shaft, when
9B060S-□N(M)	13	15	exceeds that will reduce motor service life. If axial loading is needed, we
9B090S-□N(M)	16	17	recommend applying indirect transmission, such as: couplings, belts, chains, etc

◆ Pinion shaft type (Gearhead attached)

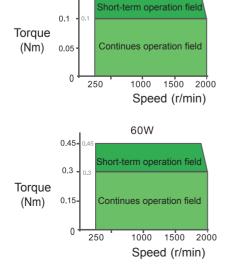
Madal		Permissible overhur	ng load (Unit: Kg f)	Permissible thrust load
Model	Gear ratio	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)
6B020P-□N(M)	3, 3.6, 5	10	15	
+ 6D□ 6B040P-□N(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	15	20	4
+ 6D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	20	30	
9B060PD-□N(M)	3, 3.6, 5	30	40	
+ 9D□ 9B090PD-□N(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15
+ 9D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65	

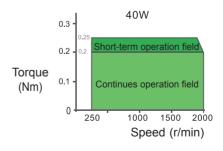
* Motor 6B020S-□N(M)... etc, please fill power voltage in □. □ : indicate single phase AC110V~115V, □ : indicate single phaseAC220~230V

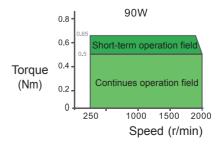
0.15

■ Speed - Torque characteristic diagrams

20W







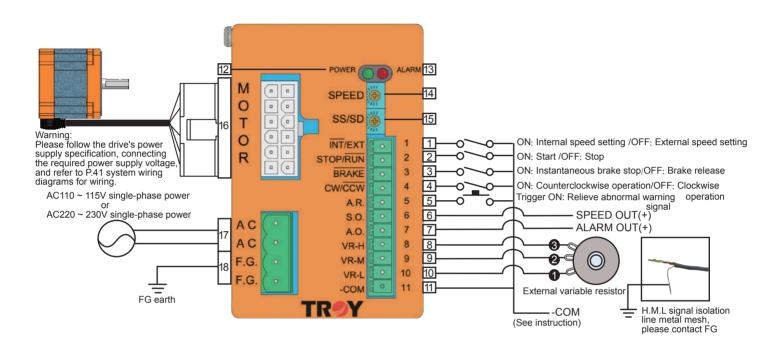
^{*} Gearhead 6D□/9D□, please fill Gearhead in □.



SBS series

■ Driver panel functions and wiring instructions

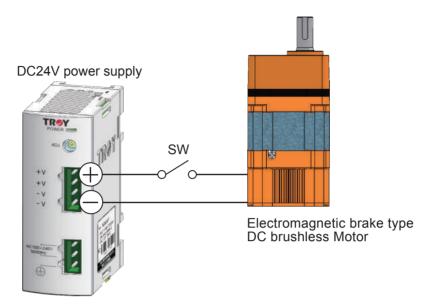




Number	Panel marked	Function	Explanation
1	INT/EXT	Speed setting mode switch to select the input	Internal / external speed setting mode switching selection
2	STOP/RUN	Stop/Start signal input	Stop / start signal switching input
3	BRAKE	Instantaneous brake stop signal input	Executive instantaneous brake stop / brake release signal switch input
4	CW/CCW	The direction of rotation switch to select the input	Clockwise/counterclockwise operation switch selection
5	A.R.	Warning signs release abnormal input	AR trigger input contacts (continuous "L" state 10ms) to release the error warning signal
6	S.O.	Speed signal output	When Motor speed is detected using, digital signal output 12 Pulse / rev
7	A.O.	Abnormal warning signal output	Overload, overheating, over voltage, low voltage, disconnection of any of a protective function is activated, Motor stops naturally, and outputs an abnormality warning signal
8	VR-H		
9	VR-M	External speed setting input	An external connection terminal variable resistor or external DC voltage (0 \sim 5V) Speed control range: 250 \sim 2000r / min
10	VR-L		
11	-COM	Control signal grounding	GND contact input and output a control signal common ground wire, and the external DC power
12	POWER	Power Indicator	Input power LED (green) lights
13	ALARM	Abnormal indicator	Overload, overheating, over voltage, low voltage, disconnection of any of a protective function is activated LED (red) lights
14	SPEED	Internal speed setting key	20 ~ 90W speed control range: 250 ~ 2000r / min
15	SS/SD	Slow start, stop time setting key	Slow start 0.5 ~ 8 sec; slow stop 0.5 ~ 7sec
16	MOTOR	Motor wiring connector	Motor and Driver connection
17	AC	Power, voltage input terminal	AC power voltage input connection
18	FG	Power ground terminal	Power ground connection

U

■ Motor electromagnetic brake wiring instructions



◆Operation instruction

Motor start/Motor stop with external electromagnetic brake operating procedures: Motor start: Must energize external electromagnetic brake before the Motor starts

Step :	External electromagnetic brake power ON
	Attracting waiting time (This is the time of the external electromagnetic brake actuation, the purpose: to keep the force is released)
	Motor Driver starting signal ON
	Motor starts running
Motor Stop :	The Motor is stopped before the operation do not yet fully external electromagnetic brake power.
Step :	Motor Driver stop signal ON
	Wait 0.2sec (reference value, this is the operation of the Motor to a complete stop time)
	complete step time)
	External electromagnetic brake power is turned OFF
	Waiting for the release time (This is the external electromagnetic brake actuation time, purpose: To generate holding force)

Precautions

1. This series of external electromagnetic brake using the brake power is part of the hold-type.

Motor stopped (a holding force)

- 2.External electromagnetic brake is designed to allow the Motor stops when the holding force has to be used as a safety brake, electromagnetic brake, do not use this as a Motor positioning or emergency brake applications.
- 3.Always to pull the Motor before starting the external electromagnetic brake energized (means no brakes); Motor stopped before the operation do not yet fully external electromagnetic brake power (expressed brakes).
- 4. External electromagnetic brake suction time and release time value refer to the product specification. 5. Motor brakes to stop for about 0.2sec (test conditions in the Motor no-load speed 3000r / min, the electromagnetic brake is energized, the brake actuator signal ON time of the Driver, this time as a reference base, but the actual length of time will stop according to the inertia load or frictional load ... different load patterns and has fluctuated.
- 6.We recommend to do the actual measuring device operating time at the time of commissioning.

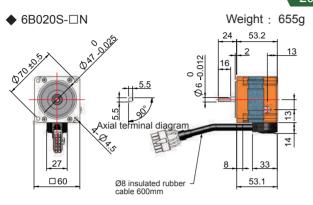


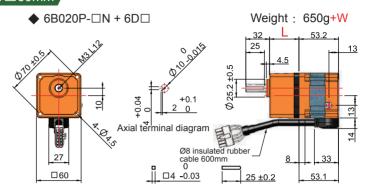
SBS series

■ Dimensions - Motor/Gearhead

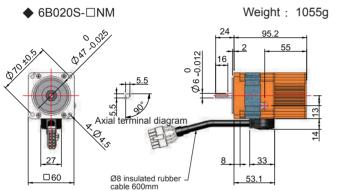
Round shaft type Gear shaft type

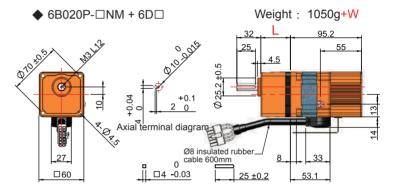
20W/□60mm



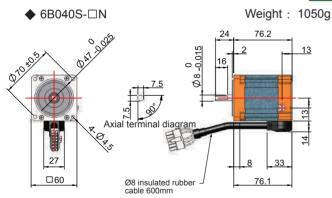


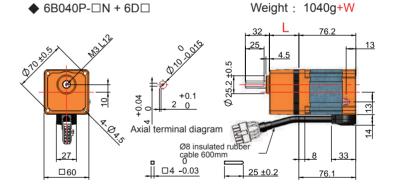
Unit: mm

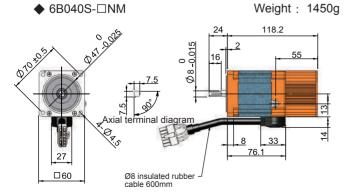




40W/□60mm

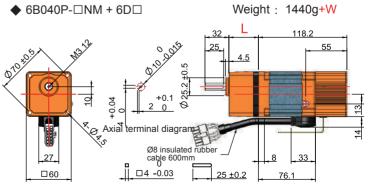






* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

6B040P-□NM + 6D□



* 6B pinion shaft type 6D3-6D360, Gearhead length L and weight W specification as following:

	Model	6D3~6D20	6D25~6D100	6D120~6D360
Gearhead	Length L (mm)	39.5	39.5	43.5
	Weight W (g)	300	325	365

B S

Motor selection

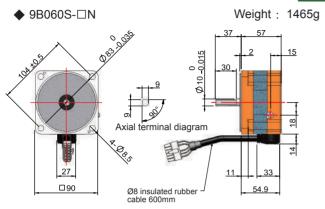
Dimensions - Motor/Gearhead

Round shaft type

Gear shaft type

Unit: mm

60W/□90mm



Weight: 1440g+W ◆ 9B060PD-□N + 9D□ NOA KOE Axial terminal diagram Ø8 insulated rubb cable 600mm □6 <u>-0.03</u> □90

◆ 9B060S-□NM Weight: 2215g 704.20.52 terminal diagran Ø8 insulated rubber cable 600mm

Weight: 2190g+W 9B060PD-□NM + 9D□ 56.5 Axial terminal diagram Ø8 insulated rubbe 0 □6 **-**0.03 54.9

90W/□90mm

Weight: 2380g

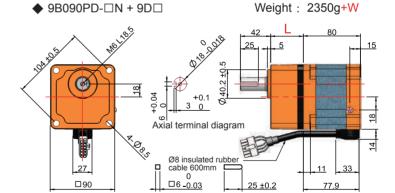
Weight: 3130g

15 704,505 18 terminal diagram ¥.00,5

♦ 9B090S-□N

□90

◆ 9B090S-□NM



70A.x0.52 Axial terminal diagram

Ø8 insulated rubber cable 600mm

Ø8 insulated rubber cable 600mm

◆ 9B090PD-□NM + 9D□

Weight: 3100g+W Axial terminal diagram Ø8 insulated rubber cable 600mm □6 <u>-0.03</u> 25 ±0.2 □90 77.9

* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

* 9B pinion shaft type 9D3-9D360, Gearhead length L and weight W specification as following:

| Model | 9D3~9D20 | 9D25~9D100 | 9D120~9D360 |

nead Length L (mm 45.5 58.5 64.5 Weight W (g) 860 1125 1265



■ Dimensions - Driver

SBS series

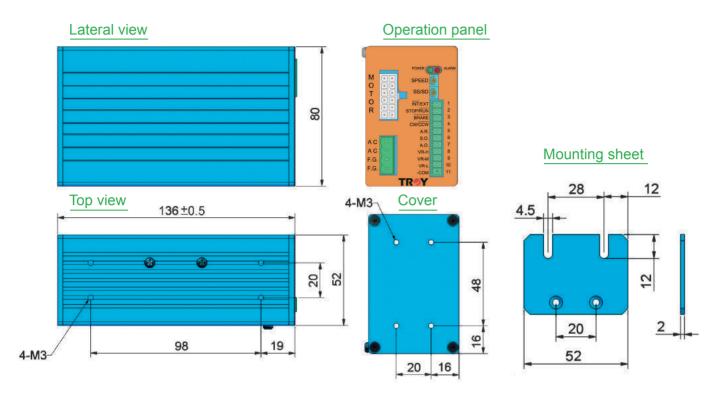
Unit: mm

Model : SBD020- \square N/SBD040- \square N

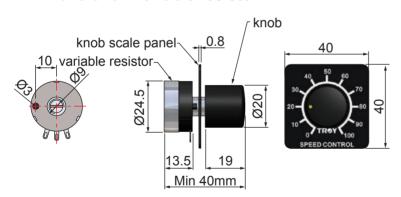
SBD060-□N/SBD090-□N

Dimensions are common

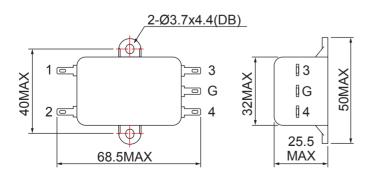
Weight: 530g



Dimensions - Variable resistor



■ Dimensions - Power supply noise filter



* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

Weight: 30g

■ Machanism: 【Op	perating of larg	e index tal	ole]		Date dd/mm/yy
Company name:	Co	ntact perso	n:	Department/T	ītle:
TEL:	FAX:		Application:	Use a	area:
Power input: □Single	e -phase AC:	V □Three	e-phase AC:V	□DC: <u>V</u>	Frequency: Hz
□9 s □0	Regulated speed single direction retop time: Section to the section retop time in the section retords and the section retords are section retords and the section retords are section retords and the section retords are secti	(Range: un \ stop \ r ond/Sequer er clockwise Sequence \	_ rpm ~ rpm)	/ated time: \$ IlSequence :Second/Se	, , , , , , , , , , , , , , , , , , ,
DC □D	orque brushless motor BS Series	: □BMS Se	□Reversible □S ries □BS Series phase □5 phase		
(Mechanism referer	nce]	-	ase sketch your ac of mechanism]	tual transmissi	on
Obje					
Drive mechanism a	and operating da	ta 】			
Obj	ect mass		W =	kg	
Inde	ex table diamete	r	DT =	cm	
Wid	th		LT =	cm	
Mat	erial		ρ =		
Pos	itioning angle	*(note)	θ =	deg	
Pos	itioning time	*(note)	To =	sec	
Sto	pping accuracy		±	mm	
*(nc	te)Please enter	the max sp	eed		
Recommendation pro	oducts (Selecte	d specs) :			

After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

■ Machanism:	Lead	screw]					D	ate dd/mn	1 / уу
Company name:			Conta	ct person:		Departn	nent/Tit	le:	
TEL:		FAX:			Application:		Use ar	ea:	
Power input: □Si	ngle -pl	nase AC	:V	□Three	-phase AC:V	□DC:	V	Frequency:	Hz
Activated mode:	□Regu □Singl stop □Clock	ulated sp le direction time: kwise/co : Seco	eed (Ron run Seconominate conditions)	ange: stop \ ru d/Sequen lockwise	tinuously → □Rat rpm ~rpm) un · stop → (Activ ce; Run, stop total repeated → (CW: CCW:Second/	ated tin	ne: S quence : cond/Se	/Minutes)	uence,
·	□Torqu DC brus □DBS	e shless m Series	notor: □	IBMS Ser	□Reversible □Spies □BS Series □ Dhase □5 phase				
Mechanism ref	W	Dbject Level	W a		Please sketch part of mechan	-	ctual tra	nsmission	
Drive mechanis	sm and	operatin	g data)						
Work+Table m	ass		W = _	kg	frictional coeffici	ent of		μ =	_
Screw angle			$\alpha = $ _	deg	sliding surfaces			L =	
Screw shaft di	ameter		D _B = _	cm	Positioning dista	ance	*(note)	To =	_sec
Screw Length			L _B = _	cm	Positioning time		*(note)	F _A =	_kg
Screw pitch			P _B = _	cm	Push / Pull force			±	
Material			ρ = _		Stopping accura	асу			
Screw efficien	су		$\eta = $ _						
Internal friction	nal coef	ficient of	# μ ₀ =_						
pilot pressure	nut				*(note)Please e	nter the	e max s	peed	

Recommendation products (Selected specs) :

^{*} After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

■ Machanism: 【	Belt ar	nd pulle	ey]						ate dd/mm	1 уу
Company name:			Contact p	person:		I	Departr	nent/Ti	tle:	
TEL:		FAX:			Application	:		Use a	rea:	
Power input: □Si	ngle -ph	ase AC:	V 🗆	Three	-phase AC:	V	□DC:	V	Frequency:	Hz
Activated mode:	□Regul □Single stop ti □Clock	ated specification at the second seco	eed (Rangon run se Second/Sunter cloc	ge: top \ ru Sequen kwise ence \	rpm ~rp	m) (Activ p total (CW:	ated tin	ne: uence :ond/Se		ience,
]]	□Torque DC brusl □DBS S	e hless m series	otor: □BN	ฟS Ser		eries I			⊐Magnetic bi □UBS Serie	
DP2 FA	Object Le		Motor	_	ase sketch y t of mechani		ctual tra	ansmis	sion	
Drive mechanis	sm and o	perating	g data]							
Work + Table +	Pulley	W =	kg	Belt `	pulley efficie	ency			η =	
Screw angle		α =	deg	friction	nal coefficien	t of sl	iding su	urfaces		
Pulley diamete	r	D _P 1 =	cm		oning distand	•	ote)		L =c	m
Width		L _P 1 =			oning time *(note)			To=s	
Material				Push /	Pull force				F _A =k	
Pulley diamete			cm	Stopp	ing accuracy	′			±r	nm
Width		L _P 2 =								
Material		ρ2 =		*(note	Please ente	r the	max sp	eed		

 $\label{lem:Recommendation products} \mbox{ (Selected specs) } \mbox{ : }$

^{**} After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

Company name:		Contact person:	•	Departi	ment/Ti	tle:	
	FAX:		Application:		Use a		
Power input: ☐Single -t	hase AC	· V DThree		V ΠDC·			Hz
□Sing stop □Clo Sto Sto Sto Required motor: AC ind □Torq DC bri	gle direction direction direction direction direction module.	on operating conceed (Range: on run \ stop \ ru Second/Sequen ond/Sequence \ uence/Minute) otor: □Induction	tinuously → □I rpm ~rpm) un · stop → (Acce; Run, stop to repeated → (C' CCW:Seco	Rated spectivated tire of talSection Sequel Speed constants.	me: \$ quence cond/Se nce \	/Minutes) equence	ake
C Drive mechanism and mechanism and fill in	d operatin	_	he space below		he outli	ine of your dri	

applicable product for you as soon as possible