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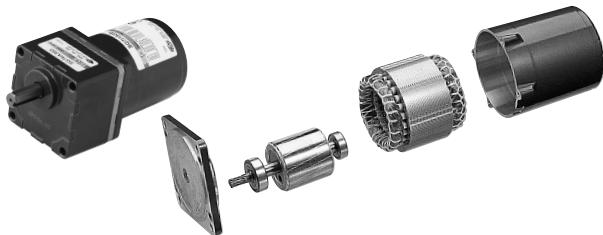
INDUCTION MOTOR

INDEX

CHARACTERISTICS OF INDUCTION MOTOR	33
INDUCTION MOTOR 6W(□60mm)	34
INDUCTION MOTOR 15W(□70mm)	36
INDUCTION MOTOR 25W(□80mm)	38
INDUCTION MOTOR 40W(□90mm)	40
INDUCTION MOTOR 60W(□90mm)	42
INDUCTION MOTOR 90W(□90mm)	44

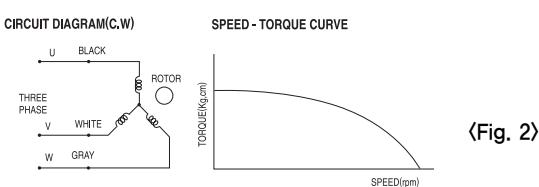
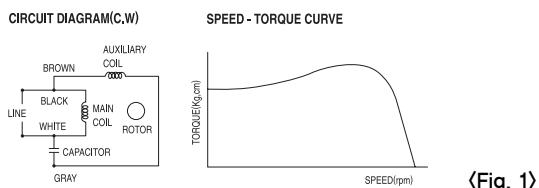


Characteristics of INDUCTION MOTOR



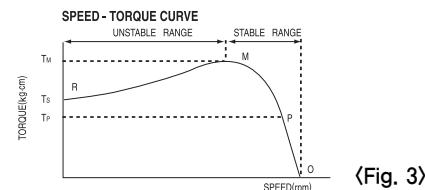
1. Characteristics of INDUCTION MOTOR

- A small induction motor usually means the condenser – run induction motor. This motor always uses both auxiliary winding and condenser not only when starting but also during operation. Generally, its starting torque isn't great, but its structure is simple reliable and efficient. Refer to (Fig. 1).
- The motor can be used in continuous rated operations.
- The number of rated rotation of the motor varies depending on the load imposed on it.
- It is suitable for operations that do not require the speed control.
- Its insulation class is E, SPG's UL conformance motor is class A.
- There are two types. One is a condenser-run single-phase induction motor and the other is a three-phase induction motor.
- Since the single-phase motor is a condenser-run induction motor, it provides high efficiency and low noise.
- There are A(100V type), B(200V type) of the power of Single-phase MOTOR.
- For a single-phase induction motor, make sure that the condenser complies with the capacity of the motor.
- For a single-phase induction motor, reversing the direction of the rotation within a short time during operation is not possible due to adverse exerting of the inertia torque against reversing. Thus, stop the motor first and change the rotational direction next.
- An induction motor is driven by a three-phase power source, the three-phase motor provides high efficiency, relatively great starting torque, and high reliability. The three-phase motor is popular as a general-purpose motor.
- There are T(200V type), S(400V type) Power of three-phase MOTOR. (Refer to (Image2))



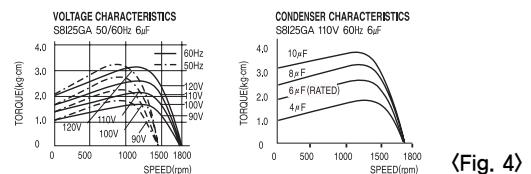
2. Characteristics of Rotation and TORQUE

- Under a constant voltage, the relationship between the number of rotation and the torque is as shown in (Fig. 3). With no-load, the number of rotation roughly approximates the number of synchronous rotation, but as the load increases, the number of rotation decreases and approaches to the speed(rpm) indicated by the point P where the torque T_p horizontally meets the load curve.
- When the load is further increased and reaches the point M, the motor stops at the point R because the motor no longer generates further torque. Therefore, the leg R-M is referred to as an unstable zone and the leg M-O is a stable zone for operation.



3. Characteristics of Voltage and CONDENSOR

- The Characteristics of voltage can be represented by the torque's characteristics about the applied voltage. The torque of induction motor changes proportionate to twice the voltage.
- The characteristics of torque also change according the capacity of the condenser.
- As the capacity of the condenser boost, the starting torque and stalling torque increase. But if the capacity increases by 2.5~3.0 folds, the operating torque decreases and the starting torque do not increase.
- As a simple method to increase the torque when the induction motor is short on torque, either the voltage or the condenser capacity can be increased to continue the operation. In this case, the loss input of the motor increases and the temperature rises rapidly.
- However, if the motor must be run with insufficient torque, take measures to let the motor release heat as much as possible and operate the motor while keeping the temperature of the motor's housing below 90°C. Refer to (Fig. 4).

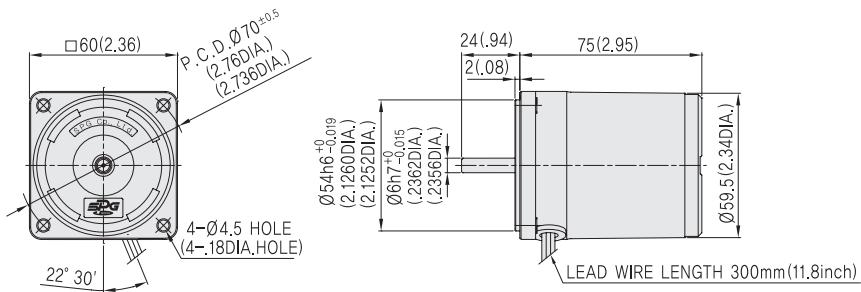


GENERAL SPECIFICATION OF INDUCTION MOTORS

ITEM	SPECIFICATION
Insulation Resistance	100MΩ or more when 500V megger is applied between the windings and the housing after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5kV at 50/60Hz applied between the windings and the case after rated motor operation under normal ambient temperature and humidity.
Temperature Rise	80°C or less increase measured by thermometer after rated operation.
Insulation Class	Class B(130°C)
Overheat Protection Device	Built-in THERMAL PROTECTOR (automatic return type) : Open 120°C±5°C Close 76°C±15°C
Ambient Temperature	-10°C ~ 40°C
Ambient Humidity	85% maximum(non condensing)

MOTOR

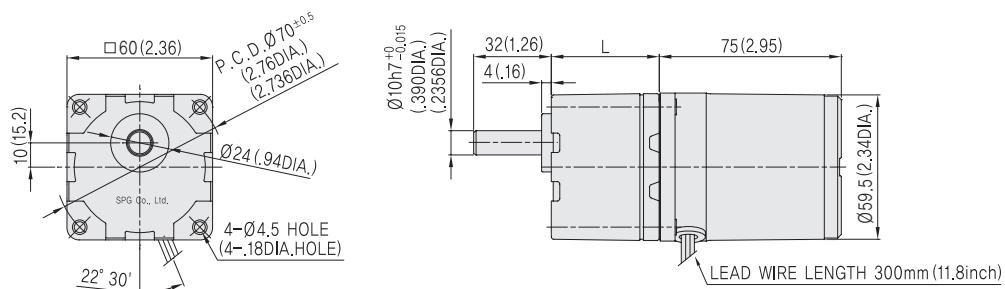
Unit : mm(inch)



MOTOR OUTPUT SHAFT	GEAR TYPE	D-CUT TYPE	STRAIGHT TYPE
	SG6I06G□	SG6I06D□	SG6I06S□
	<p>Front view dimensions: 15.2(.60)</p>	<p>Front view dimensions: Ø6h7^{+0.015} (.2362DIA.) (Ø256DIA.), 5.5^{+0.1} (.217) (213), 24(.94), 20(.79)</p>	<p>Front view dimensions: Ø6h7^{+0.015} (.2362DIA.) (Ø2355DIA.), 24(.94)</p>

GEARED MOTOR

Unit : mm(inch)

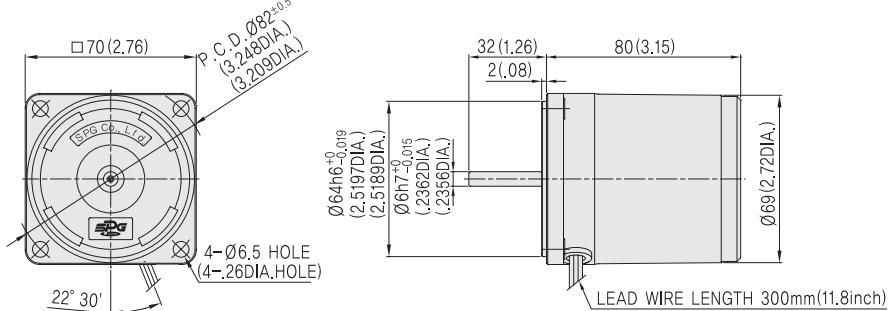


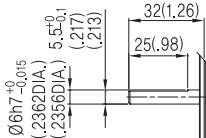
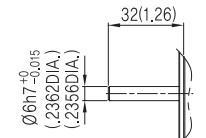
GEAR HEAD OUTPUT SHAFT	KEY TYPE	D-CUT TYPE	STRAIGHT TYPE
	SG6KA□	SG6DA□	SG6SA□
	<p>Front view dimensions: 2.5^{+0.1} (.102) (Ø.098), 32(1.26), 25(.98), 10h7^{+0.05} (.3337) (.3331), 4^{+0.03} (.159) (.157)</p>	<p>Front view dimensions: 25^{+0.2} (.992) (.976), 4^{+0.03} (.159) (.157)</p>	<p>Front view dimensions: 32(1.26), 25(.98), 10h7^{+0.05} (.3337) (.3331), 9^{+0.1} (.334) (.330)</p>

MODEL		GEAR RATIO	L	WEIGHT(kg)
GEAR HEAD	SG6□A□	5~25	34	0.28
		30~120	38	0.33
		150~360	43	0.37
MOTOR	SG6I06□□			0.7

MOTOR

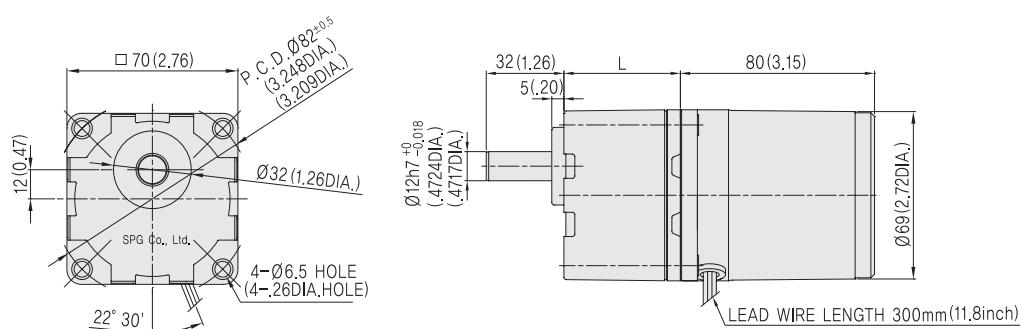
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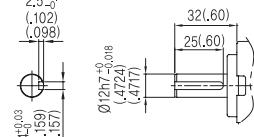
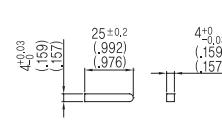
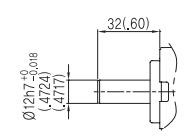


MOTOR OUTPUT SHAFT	GEAR TYPE	D-CUT TYPE	STRAIGHT TYPE
	SG7I15G□	SG7I15D□	SG7I15S□
			

GEARED MOTOR

Unit : mm(inch)

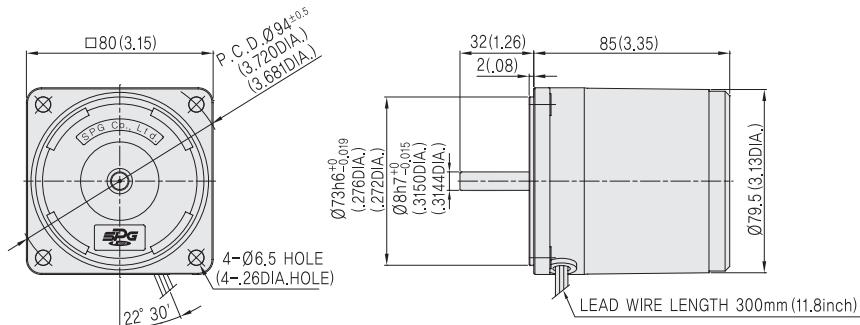


GEAR HEAD OUTPUT SHAFT	KEY TYPE	D-CUT TYPE	STRAIGHT TYPE
	SG7KA□	SG7DA□	SG7SA□
			

MODEL		GEAR RATIO	L	WEIGHT(kg)
GEAR HEAD	SG7□A□	5~120	43	0.42
		150~360	48	0.52
MOTOR	SG7I15□□			1.04

MOTOR

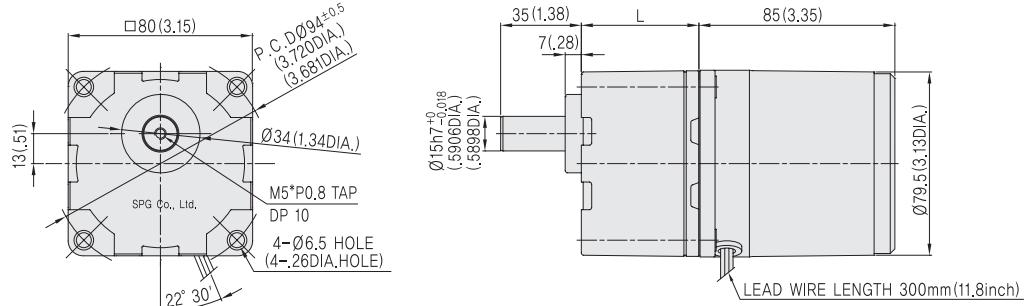
Unit : mm(inch)



MOTOR OUTPUT SHAFT	GEAR TYPE	KEY TYPE	D-CUT TYPE	STRAIGHT TYPE
	SG8I25G□	SG8I25K□	SG8I25D□	SG8I25S□

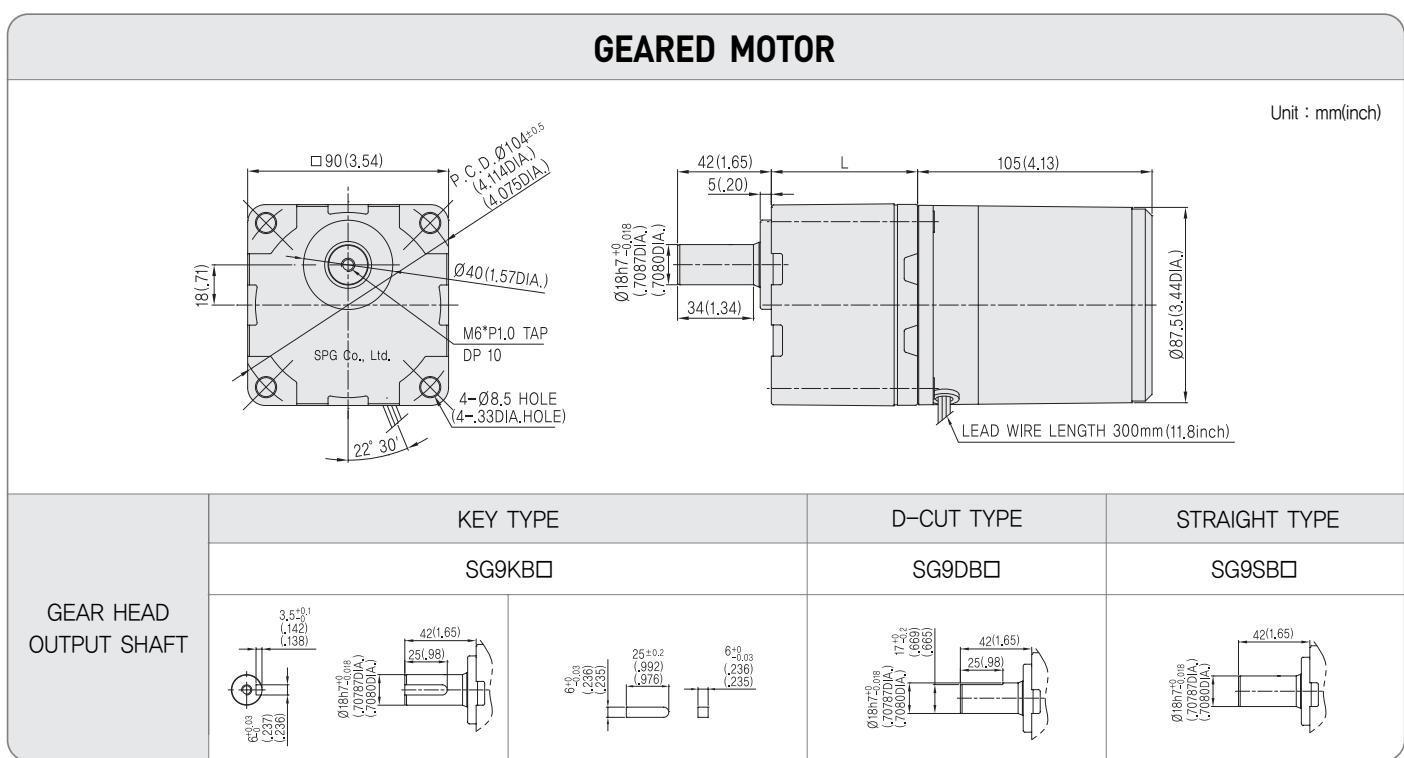
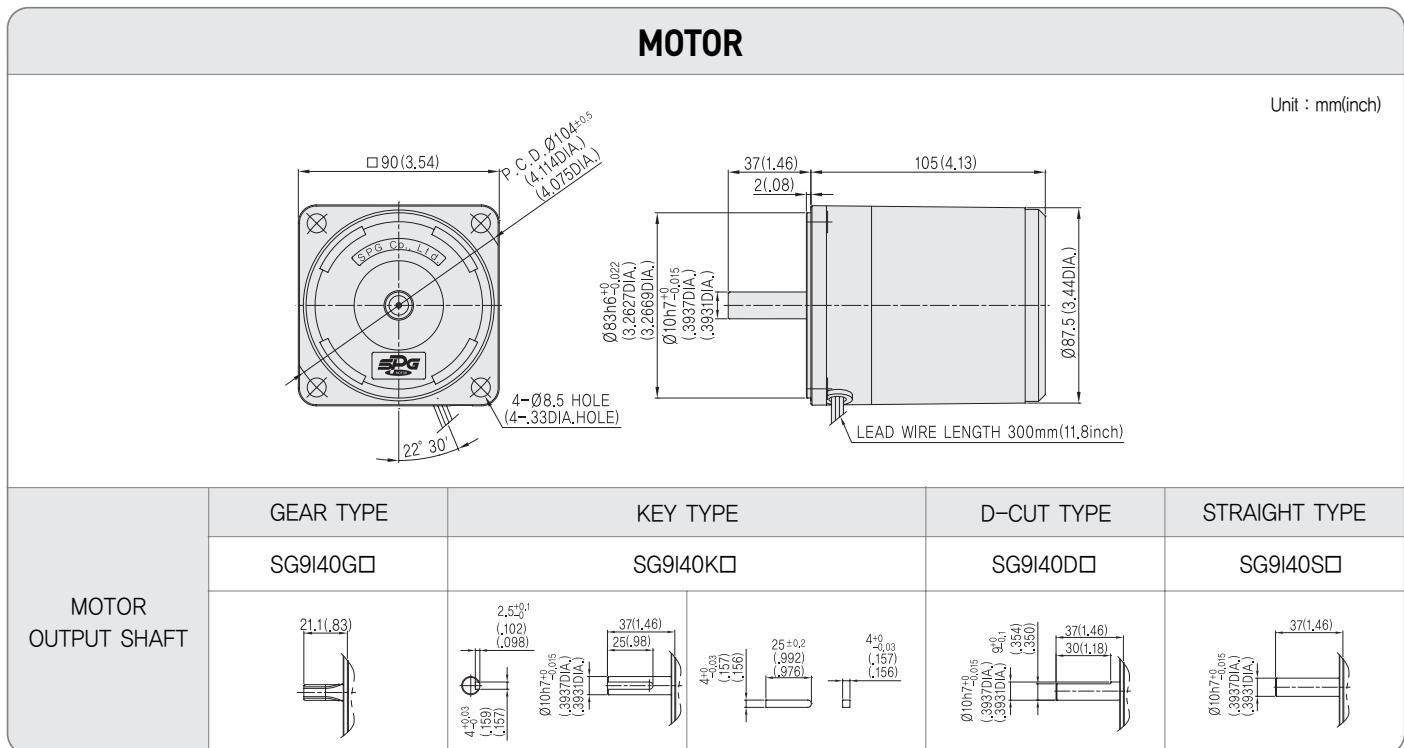
GEARED MOTOR

Unit : mm(inch)

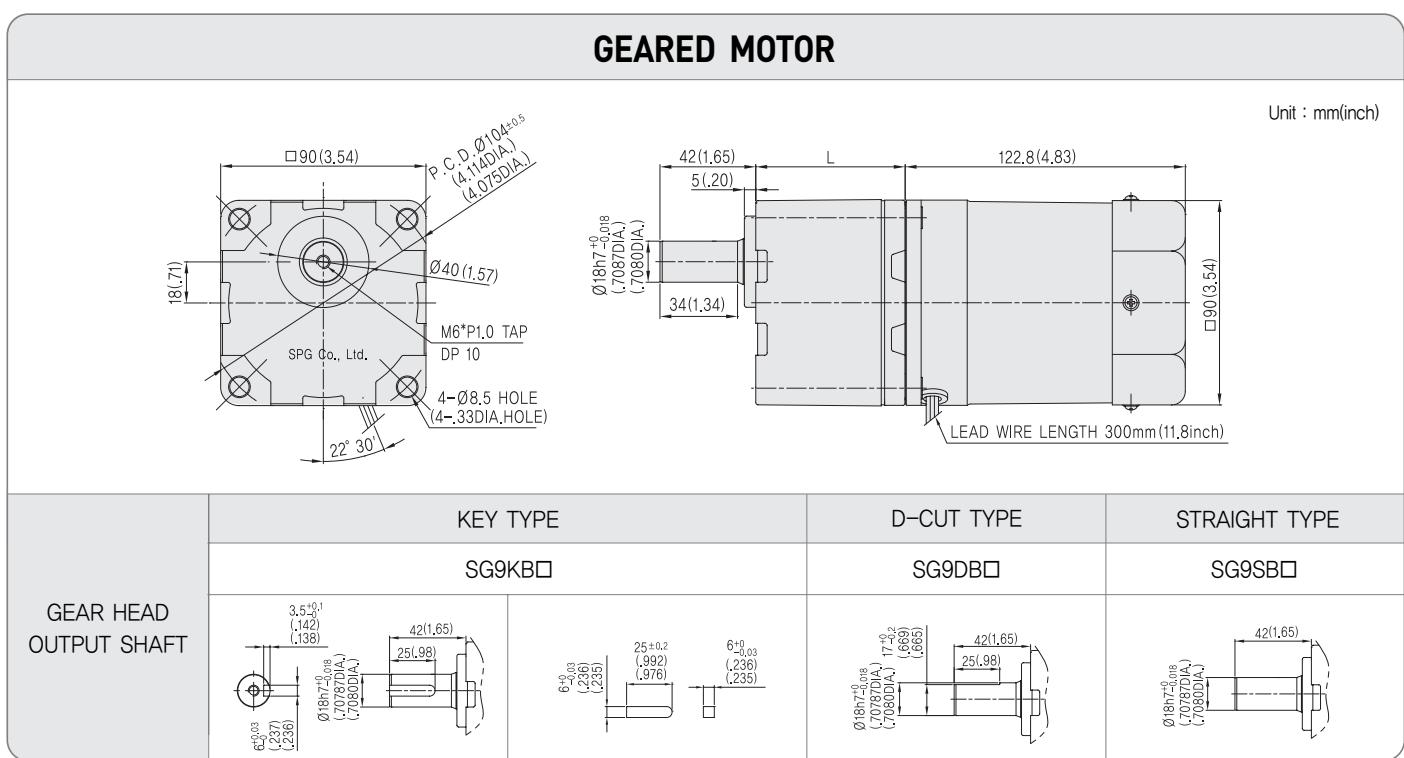
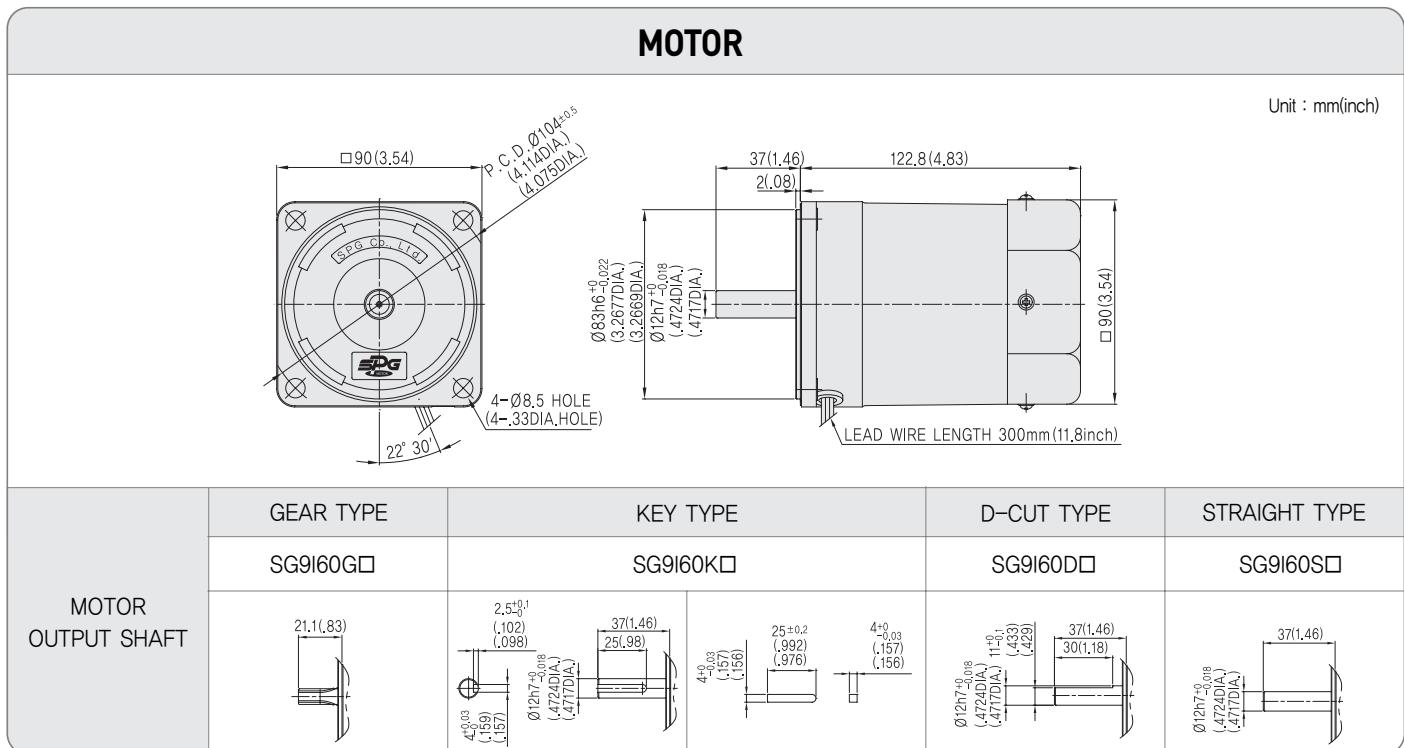


GEAR HEAD OUTPUT SHAFT	KEY TYPE	D-CUT TYPE	STRAIGHT TYPE
	SG8KA□	SG8DA□	SG8SA□

MODEL		GEAR RATIO	L	WEIGHT(kg)
GEAR HEAD	SG8□A□	5~25	41	0.61
		30~120	46	0.72
		150~360	51	0.80
MOTOR	SG8I25□□			1.46



MODEL		GEAR RATIO	L	WEIGHT(kg)
GEAR HEAD	SG9□B□	5~20	45	0.85
		25~100	58	1.15
		120~300	64	1.30
MOTOR	SG9I40□□			2.30



MODEL		GEAR RATIO	L	WEIGHT(kg)
GEAR HEAD	SG9□B□	5~20	45	0.85
		25~100	58	1.15
		120~300	64	1.30
MOTOR	SG9I60□□			2.44

MOTOR				
Unit : mm(inch)				
				LEAD WIRE LENGTH 300mm(11.8inch)
MOTOR OUTPUT SHAFT	GEAR TYPE	KEY TYPE	D-CUT TYPE	STRAIGHT TYPE
	SG9I90G□	SG9I90K□	SG9I90D□	SG9I90S□

GEARED MOTOR				
Unit : mm(inch)				
				LEAD WIRE LENGTH 300mm(11.8inch)
GEAR HEAD OUTPUT SHAFT	KEY TYPE	D-CUT TYPE	STRAIGHT TYPE	
	SG9KC□	SG9DC□	SG9SC□	

MODEL		GEAR RATIO	L	WEIGHT(kg)
GEAR HEAD	SG9□C□	5~15	45	0.85
		18~40	58	1.15
		50~200	70	1.42
MOTOR	SG9I90□□			2.93